SONY

# Diagonal 5.68mm (Type 1/3.2) Frame Readout CCD Image Sensor with Square Pixel for Color Cameras

#### Description

The ICX434AQ is a diagonal 5.68mm (Type 1/3.2) interline CCD solid-state image sensor with a square pixel array and 2.02M effective pixels. Frame readout allows all pixels' signals to be output independently within approximately 1/7.5 second. Also, the adoption of high frame rate readout mode supports 30 frames per second which is four times the speed in frame readout mode. This chip features an electronic shutter with variable charge-storage time. Adoption of a design specially suited for frame readout ensures a saturation signal level equivalent to when using field readout. High resolution and high color reproductivity are achieved through the use of R, G, B primary color mosaic filters. Further, high sensitivity and low dark current are achieved through the adoption of Super HAD CCD technology.

This chip is suitable for applications such as electronic still cameras, PC input cameras, etc.

#### Features

- Supports frame readout
- High horizontal and vertical resolution
- Supports high frame rate readout mode: 30 frames/s
- Square pixel
- Horizontal drive frequency: 18MHz
- No voltage adjustments (reset gate and substrate bias are not adjusted.)
- R, G, B primary color mosaic filters on chip
- High color reproductivity, high sensitivity, low smear
- Continuous variable-speed shutter
- Low dark current, excellent anti-blooming characteristics
- 16-pin high-precision plastic package (top/bottom dual surface reference possible)

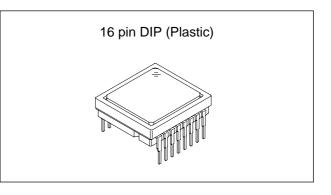
### **Device Structure**

- Interline CCD image sensor
- Image size:
- Diagonal 5.68mm (Type 1/3.2) • Total number of pixels: 1688 (H) × 1248 (V) approx. 2.11M pixels
- Number of effective pixels: 1636 (H) × 1236 (V) approx. 2.02M pixels
- Number of active pixels: 1620 (H) × 1220 (V) approx. 1.98M pixels
- · Chip size:
- Unit cell size:
- · Optical black: Vertical (V) direction:
- Number of dummy bits:
- Substrate material:

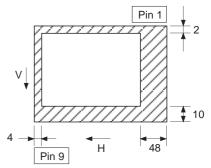
5.27mm (H) × 4.40mm (V)  $2.8\mu m$  (H)  $\times 2.8\mu m$  (V) Horizontal (H) direction: Front 4 pixels, rear 48 pixels Front 10 pixels, rear 2 pixels Horizontal 28 Vertical 1 (even fields only) Silicon

- Super HAD CCD
- \*Super HAD CCD is a trademark of Sony Corporation. The Super HAD CCD is a version of Sony's high performance CCD HAD (Hole-Accumulation Diode) sensor with sharply improved sensitivity by the incorporation of a new semiconductor technology developed by Sony Corpration.

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ICX434A



**Optical black position** (Top View)

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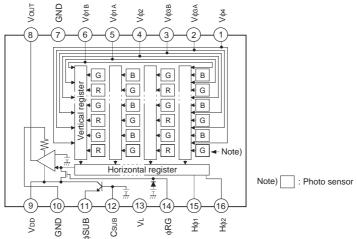
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#### **Block Diagram and Pin Configuration**

(Top View)



### **Pin Description**

Pin No.	Symbol	Description	Pin No.	Symbol	Description
1	Vφ4	Vertical register transfer clock	9	Vdd	Supply voltage
2	Vфза	Vertical register transfer clock	10	GND	GND
3	Vфзв	Vertical register transfer clock	11	φSUB	Substrate clock
4	Vø2	Vertical register transfer clock	12	Сѕив	Substrate bias <sup>*1</sup>
5	Vφ1A	Vertical register transfer clock	13	VL	Protective transistor bias
6	Vф1в	Vertical register transfer clock	14	φRG	Reset gate clock
7	GND	GND	15	Hφ1	Horizontal register transfer clock
8	νουτ	Signal output	16	Hø2	Horizontal register transfer clock

\*1 DC bias is generated within the CCD, so that this pin should be grounded externally through a capacitance of 0.1µF.

### **Absolute Maximum Ratings**

	Item	Ratings	Unit	Remarks
	Vdd, Vout, <b>\$RG – \$SUB</b>	-40 to +12	V	
	Vφ1Α, Vφ1Β, Vφ3Α, Vφ3Β – φSUB	-50 to +15	V	
Against	$V\phi_2, V\phi_4, V_L - \phi SUB$	-50 to +0.3	V	
	Hφ1, Hφ2, GND – φSUB	-40 to +0.3	V	
	Csub – $\phi$ SUB	-25 to	V	
	Vdd, Vout, фRG, Csub – GND	-0.3 to +22	V	
Against GND	Vφ1a, Vφ1b, Vφ2, Vφ3a, Vφ3b, Vφ4 – GND	-10 to +18	V	
	Ηφ1, Ηφ2 – GND	-10 to +6.5	V	
Against V∟	Vφ1Α, Vφ1Β, Vφ3Α, Vφ3Β – VL	-0.3 to +28	V	
	Vφ2, Vφ4, Hφ1, Hφ2, GND – VL	-0.3 to +15	V	
Detween innut electr	Voltage difference between vertical clock input pins	to +15	V	*2
Between input clock	Ηφ1 – Ηφ2	-6.5 to +6.5	V	
	$H\phi_1, H\phi_2 - V\phi_4$	-10to +16	V	
Storage temperature	-30 to +80	°C		
Guaranteed temperate	-10 to +60	°C		
Operating temperature	9	-10 to +75	°C	

\*2 +24V (Max.) when clock width < 10 $\mu$ s, clock duty factor < 0.1%.

+16V (Max.) is guaranteed for turning on or off power supply.

# **Bias Conditions**

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Supply voltage	Vdd	14.55	15.0	15.45	V	
Protective transistor bias	VL		*1			
Substrate clock	φSUB		*2			
Reset gate clock	φRG		*2			

\*1 VL setting is the VvL voltage of the vertical transfer clock waveform, or the same voltage as the VL power supply for the V driver should be used.

\*2 Do not apply a DC bias to the substrate clock and reset gate clock pins, because a DC bias is generated within the CCD.

### **DC** Characteristics

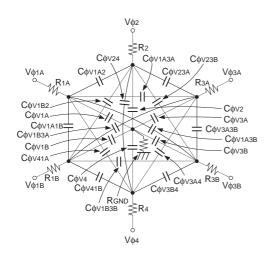
Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Supply current	Idd		6.5		mA	

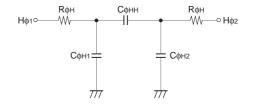
### **Clock Voltage Conditions**

Item	Symbol	Min.	Тур.	Max.	Unit	Waveform diagram	Remarks
Readout clock voltage	Vvт	14.55	15.0	15.45	V	1	
	Vvh1, Vvh2	-0.05	0	0.05	V	2	Vvн = (Vvн1 + Vvн2)/2
	Vvнз, Vvн4	-0.2	0	0.05	V	2	
	Vvl1, Vvl2, Vvl3, Vvl4	-8.0	-7.5	-7.0	V	2	Vvl = (Vvl3 + Vvl4)/2
	Vφv	6.8	7.5	8.05	V	2	$V\phi = V + n - V + n (n = 1 \text{ to } 4)$
Vertical transfer clock voltage	Vvнз – Vvн	-0.25		0.1	V	2	
voltage	Vvh4 – Vvh	-0.25		0.1	V	2	
	V∨нн			0.5	V	2	High-level coupling
	Vvhl			0.5	V	2	High-level coupling
	Vvlh			0.5	V	2	Low-level coupling
	Vvll			0.5	V	2	Low-level coupling
	Vфн	3.0	3.3	3.6	V	3	
Horizontal transfer clock voltage	Vhl	-0.05	0	0.05	V	3	
	Vcr	0.5	1.65		V	3	Cross-point voltage
	Vørg	3.0	3.3	3.6	V	4	
Reset gate clock voltage	Vrglh – Vrgll			0.4	V	4	Low-level coupling
	Vrgl – Vrglm			0.5	V	4	Low-level coupling
Substrate clock voltage	Vфsuв	21.5	22.5	23.5	V	5	

# **Clock Equivalent Circuit Constant**

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
	Сфила, Сфиза		680		pF	
Capacitance between vertical transfer clock and GND	Сфv1в, Сфv3в		1500		pF	
	<b>C</b> φν2, <b>C</b> φν4		1500		pF	
	<b>C</b> φν1A2, <b>C</b> φν3A4		100		pF	
	Сфv1в2, Сфv3в4		220		pF	
	Сфv2за, Сфv41а		30		pF	
	Сфv23в, Сфv41в		56		pF	
Capacitance between vertical transfer clocks	Сфv1аза		12		pF	
	Сфv1взв		82		pF	
	Сфилазв, Сфилвза		39		pF	
	Сф∨24		100		pF	
	Сфиала, Сфизазв		30		pF	
Capacitance between horizontal transfer	Сфн1		30		pF	
clock and GND	Сфн2		30		pF	
Capacitance between horizontal transfer clocks	Сфнн		56		pF	
Capacitance between reset gate clock and GND	Cørg		5		pF	
Capacitance between substrate clock and GND	Сфѕив		470		pF	
	R1A, R3A		270		Ω	
Vertical transfer clock series resistor	R1в, R3в		110		Ω	
	R2, R4		56		Ω	
Vertical transfer clock ground resistor	Rgnd		10		Ω	
Horizontal transfer clock series resistor	Rфн		15		Ω	



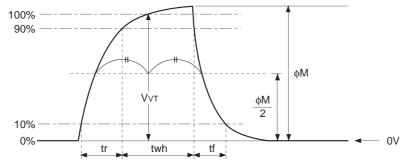


Vertical transfer clock equivalent circuit

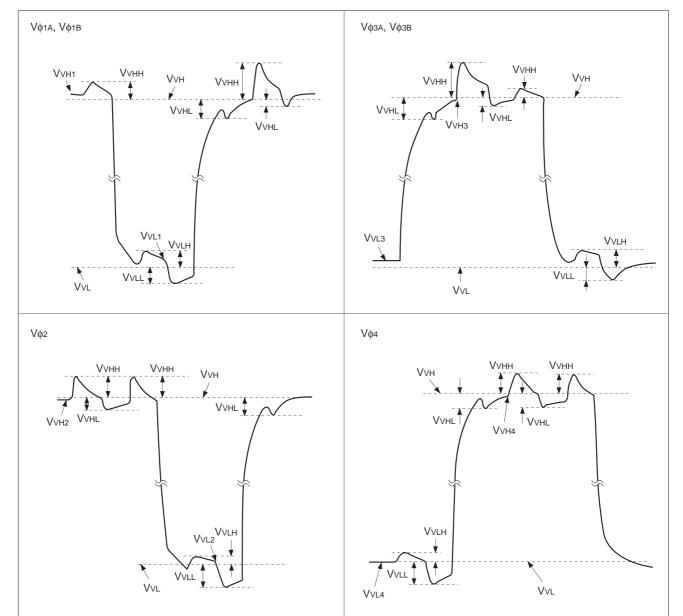
Horizontal transfer clock equivalent circuit

# **Drive Clock Waveform Conditions**

#### (1) Readout clock waveform

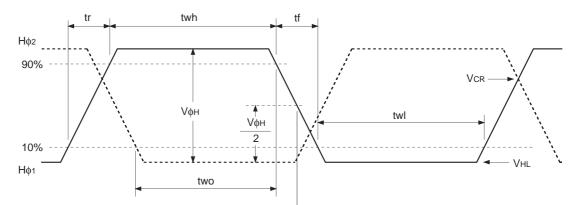






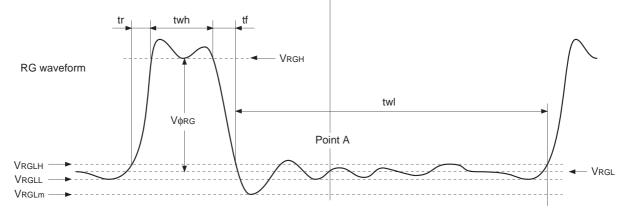
 $V_{VH} = (V_{VH1} + V_{VH2})/2$  $V_{VL} = (V_{VL3} + V_{VL4})/2$  $V_{\phi V} = V_{VHN} - V_{VLN} (n = 1 \text{ to } 4)$ 

#### (3) Horizontal transfer clock waveform



Cross-point voltage for the H $\phi_1$  rising side of the horizontal transfer clocks H $\phi_1$  and H $\phi_2$  waveforms is Vcr. The overlap period for twh and twl of horizontal transfer clocks H $\phi_1$  and H $\phi_2$  is two.

#### (4) Reset gate clock waveform



VRGLH is the maximum value and VRGLL is the minimum value of the coupling waveform during the period from Point A in the above diagram until the rising edge of RG.

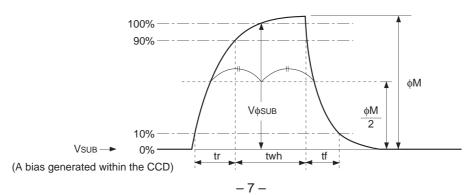
In addition, VRGL is the average value of VRGLH and VRGLL.

Assuming VRGH is the minimum value during the interval twh, then:

Vørg = Vrgh – Vrgl

Negative overshoot level during the falling edge of RG is VRGLm.

#### (5) Substrate clock waveform

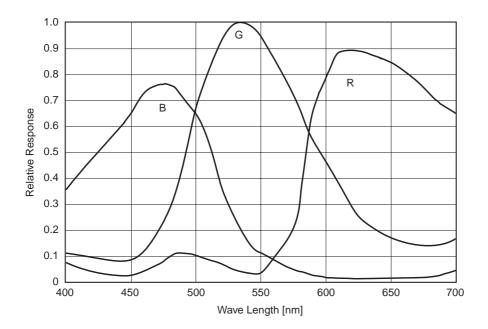


Item		Symbol		twh			twl			tr			tf		Linit	Domorko
	nem	Symbol	Min.	Тур.	Max.	Unit	Remarks									
Rea	dout clock	VT	1.36	1.56						0.5			0.5		μs	During readout
Vert cloc	ical transfer k	Vφ1Α, Vφ1Β, Vφ2, Vφ3Α, Vφ3Β, Vφ4										15		250	ns	When using CXD1267AN
ock	During	Hφ1	14	19.5		14	19.5			8.5	14		8.5	14	ne	tf ≥ tr – 2ns
ntal r clc	imaging	Hø2	14	19.5		14	19.5			8.5	14		8.5	14	ns	u ∠ u − 2115
Horizontal transfer clock	During parallel-serial	Hφ1		5.56						0.01			0.01		μs	
Hc	conversion	Hø2					5.56			0.01			0.01		μο	
Res	et gate clock	φRG	7	10			37			4			5		ns	
Sub	strate clock	фSUB	1.7	3.6							0.5			0.5	μs	When draining charge

# Clock Switching Characteristics (Horizontal drive frequency:18MHz)

ltem	Symbol		two		Unit	Remarks	
	Symbol	Min.	Тур.	Max.	Unit	Remarks	
Horizontal transfer clock	Hφ1, Hφ2	12	19.5		ns		

# Spectral Sensitivity Characteristics (excludes lens characteristics and light source characteristics)



(Ta = 25°C)

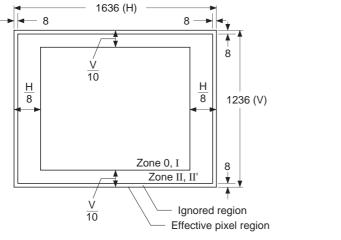
# **Image Sensor Characteristics**

ltem		Symbol	Min.	Тур.	Max.	Unit	Measurement method	Remarks
G sensitivity		Sg	200	250		mV	1	1/30s accumulation
Sensitivity	R	Rr	0.46		0.72		1	
comparison	В	Rb	0.33		0.59		1	
Saturation signa	I	Vsat	420			mV	2	Ta = 60°C
Smoor	0			-86	-76	dB	3	Frame readout mode*1
Smear		Sm		-74	-64	uБ	3	High frame rate readout mode
					20	%	4	Zone 0 and I
Video signal sha	ang	SHg			25	%	4	Zone 0 to II'
Dark signal		Vdt			8	mV	5	Ta = 60°C, 15 frame/s
Dark signal shac	ling	ΔVdt			4	mV	6	Ta = 60°C, 15 frame/s,*2
Line crawl G		Lcg			3.8	%	7	
Line crawl R		Lcr			3.8	%	7	
Line crawl B		Lcb			3.8	%	7	
Lag		Lag			0.5	%	8	

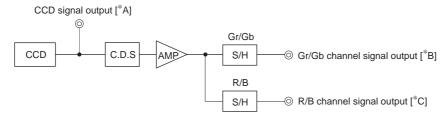
\*1 After closing the mechanical shutter, the smear can be reduced to below the detection limit by performing vertical register sweep operation.

\*2 Excludes vertical dark signal shading caused by vertical register high-speed transfer.

# Zone Definition of Video Signal Shading



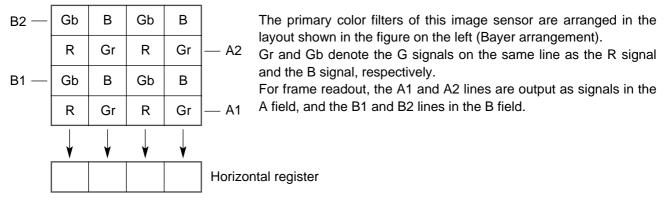
### **Measurement System**



Note) Adjust the amplifier gain so that the gain between [\*A] and [\*B], and between [\*A] and [\*C] equals 1.

# Image Sensor Characteristics Measurement Method

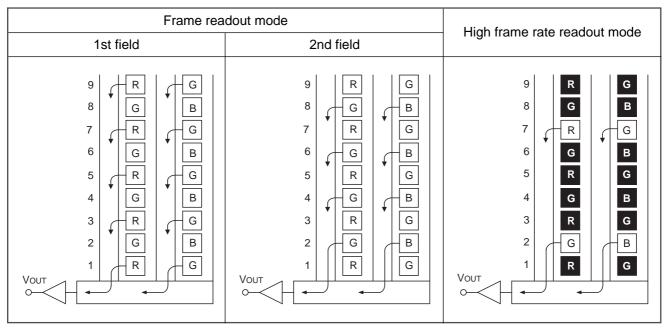
### ◎ Color coding of this image sensor & Readout



# Color Coding Diagram

#### Readout modes

The diagram below shows the output methods for the following two readout modes.



**Note)** Blacked out portions in the diagram indicate pixels which are not read out. Output starts from the line 2 in high frame rate readout mode

### 1. Frame readout mode

In this mode, all pixel signals are divided into two fields and output. All pixel signals are read out independently, making this mode suitable for high resolution image capturing.

### 2. High frame rate readout mode

All effective area signals are output in 1/4 the period for frame readout mode by reading out two lines for every eight lines. The number of output lines is 309 lines.

This readout mode emphasizes processing speed over vertical resolution.

### O Measurement conditions

- 1) In the following measurements, the device drive conditions are at the typical values of the bias and clock voltage conditions, and the frame readout mode is used.
- 2) In the following measurements, spot blemishes are excluded and, unless otherwise specified, the optical black level (OB) is used as the reference for the signal output, which is taken as the value of the Gr/Gb channel signal output or the R/B channel signal output of the measurement system.

### O Definition of standard imaging conditions

1) Standard imaging condition I:

Use a pattern box (luminance: 706cd/m<sup>2</sup>, color temperature of 3200K halogen source) as a subject. (Pattern for evaluation is not applicable.) Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter and image at F5.6. The luminous intensity to the sensor receiving surface at this point is defined as the standard sensitivity testing luminous intensity.

2) Standard imaging condition II:

Image a light source (color temperature of 3200K) with a uniformity of brightness within 2% at all angles. Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter. The luminous intensity is adjusted to the value indicated in each testing item by the lens diaphragm.

3) Standard imaging condition III:

Image a light source (color temperature of 3200K) with a uniformity of brightness within 2% at all angles. Use a testing standard lens (exit pupil distance -33mm) with CM500S (t = 1.0mm) as an IR cut filter. The luminous intensity is adjusted to the value indicated in each testing item by the lens diaphragm.

1. G sensitivity, sensitivity comparison

Set to standard imaging condition I. After selecting the electronic shutter mode with a shutter speed of 1/100s, measure the signal outputs (V<sub>Gr</sub>, V<sub>Gb</sub>, V<sub>R</sub> and V<sub>B</sub>) at the center of each Gr, Gb, R and B channel screen, and substitute the values into the following formulas.

 $\label{eq:stars} \begin{array}{l} V_G = (V_{Gr} + V_{Gb})/2 \\ Sg = V_G \times 100/30 \; [mV] \\ Rr = V_R/V_G \\ Rb = V_B/V_G \end{array}$ 

2. Saturation signal

Set to standard imaging condition II. After adjusting the luminous intensity to 20 times the intensity with the average value of the Gr signal output, 150mV, measure the minimum values of the Gr, Gb, R and B signal outputs.

3. Smear

Set to standard imaging condition II. With the lens diaphragm at F5.6 to F8, first adjust the average value of the Gr signal output to 150mV. Measure the average values of the Gr signal output, Gb signal output, R signal output and B signal output (Gra, Gba, Ra, Ba), and then adjust the luminous intensity to 500 times the intensity with the average value of the Gr signal output, 150mV. After the readout clock is stopped and the charge drain is executed by the electronic shutter at the respective H blankings, measure the maximum value (Vsm [mV]) independent of the Gr, Gb, R and B signal outputs, and substitute the values into the following formula.

$$Sm = 20 \times \log \left( Vsm \div \frac{Gra + Gba + Ra + Ba}{4} \times \frac{1}{500} \times \frac{1}{10} \right) \text{ [dB] (1/10V method conversion value)}$$

# 4. Video signal shading

Set to standard imaging condition III. With the lens diaphragm at F5.6 to F8, adjust the luminous intensity so that the average value of the Gr signal output is 150mV. Then measure the maximum (Grmax [mV]) and minimum (Grmin [mV]) values of the Gr signal output and substitute the values into the following formula.

SHg =  $(Grmax - Grmin)/150 \times 100$  [%]

5. Dark signal

Measure the average value of the signal output (Vdt [mV]) with the device ambient temperature 60°C and the device in the light-obstructed state, using the horizontal idle transfer level as a reference.

# 6. Dark signal shading

After measuring 5, measure the maximum (Vdmax [mV]) and minimum (Vdmin [mV]) values of the dark signal output and substitute the values into the following formula.

 $\Delta Vdt = Vdmax - Vdmin [mV]$ 

7. Line crawl

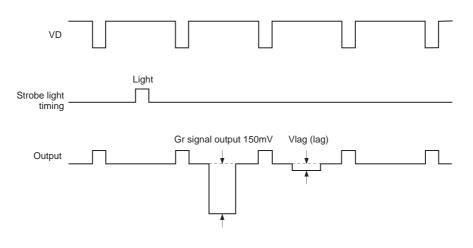
Set to standard imaging condition II. Adjusting the luminous intensity so that the average value of the Gr signal output is 150mV, and then insert R, G and B filters and measure the difference between G signal lines ( $\Delta$ Glr,  $\Delta$ Glg,  $\Delta$ Glb [mV]) as well as the average value of the G signal output (Gar, Gag, Gab). Substitute the values into the following formula.

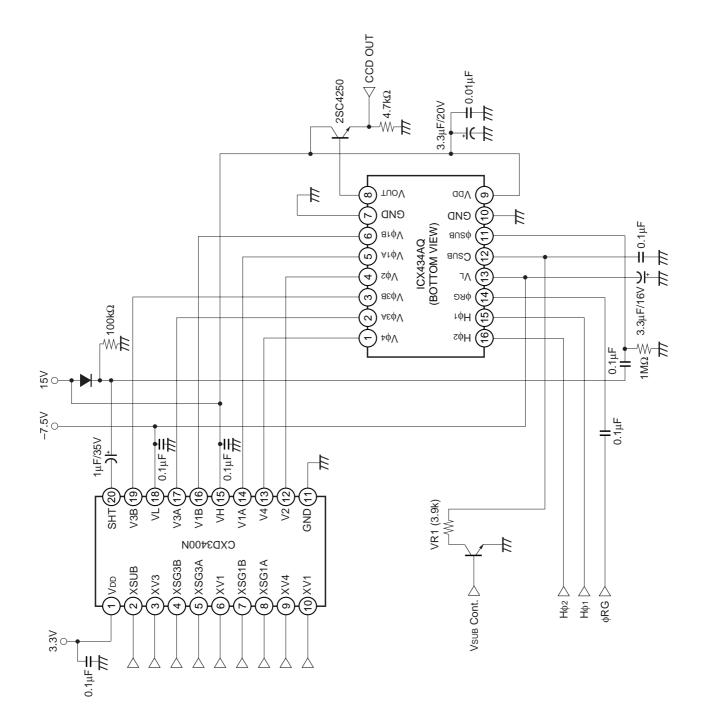
Lci =  $\Delta$ Gli/Gai × 100 [%] (i = r, g, b)

### 8. Lag

Adjust the Gr signal output value generated by strobe light to 150mV. After setting the strobe light so that it strobes with the following timing, measure the residual signal (Vlag). Substitute the value into the following formula.

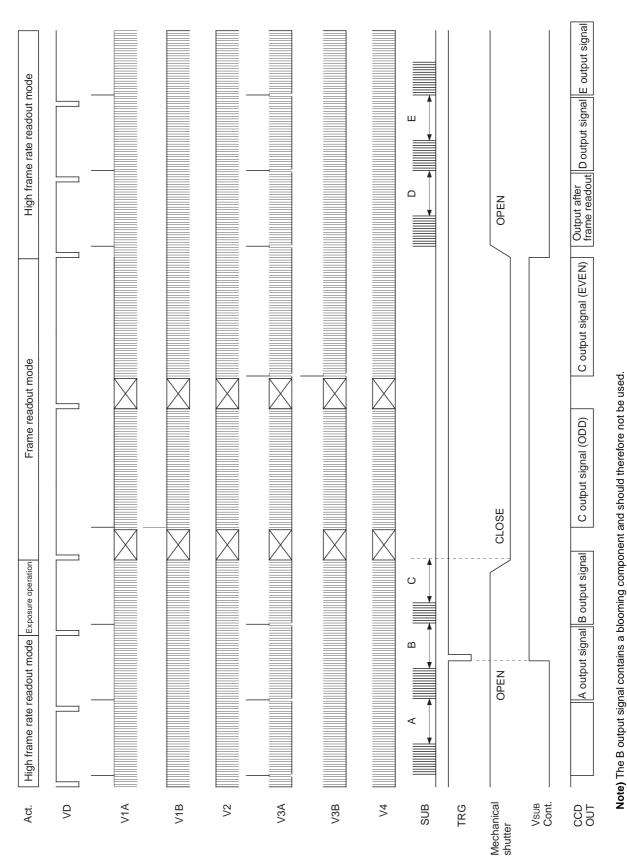
Lag = (Vlag/150) × 100 [%]





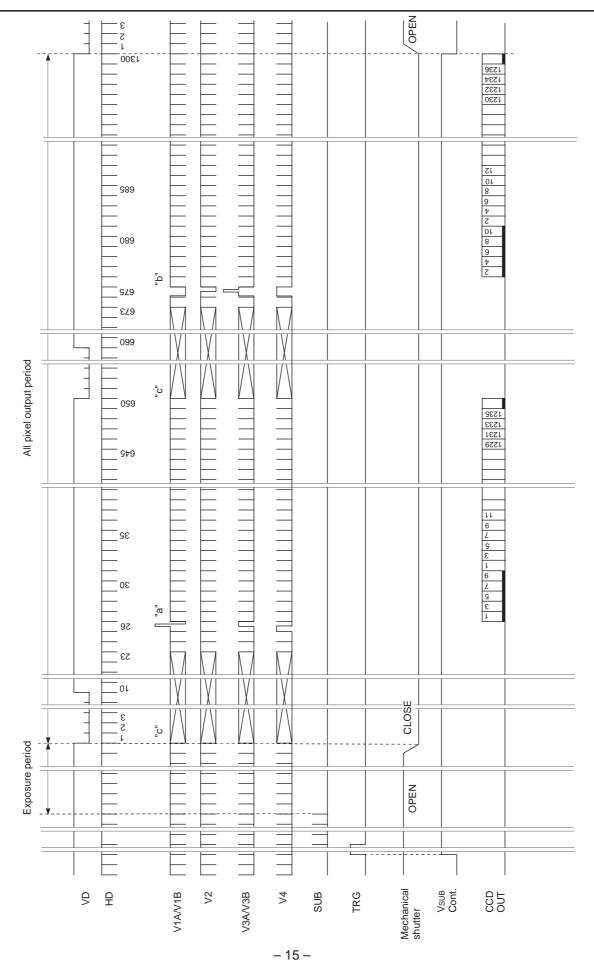
**Drive Circuit** 

Drive Timing Chart (Vertical Sequence) High Frame Rate Readout Mode → Frame Readout Mode/Electronic Shutter

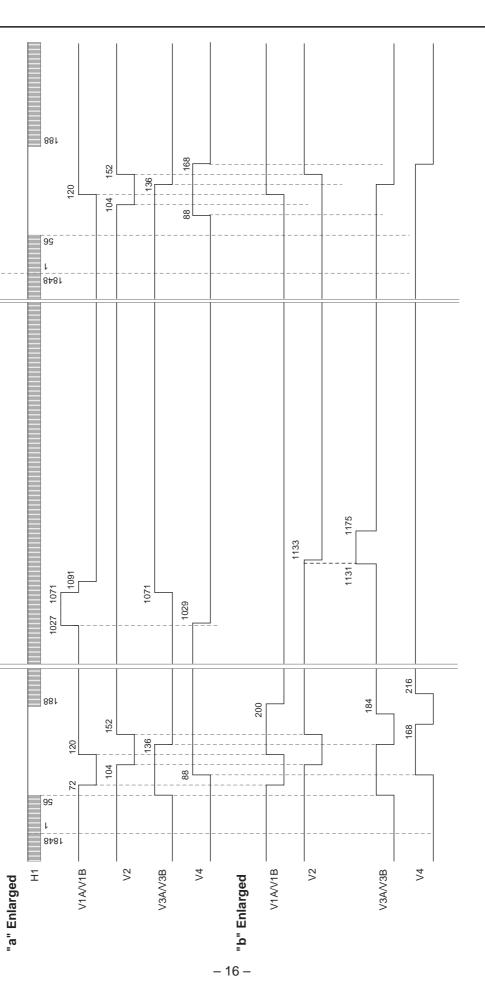


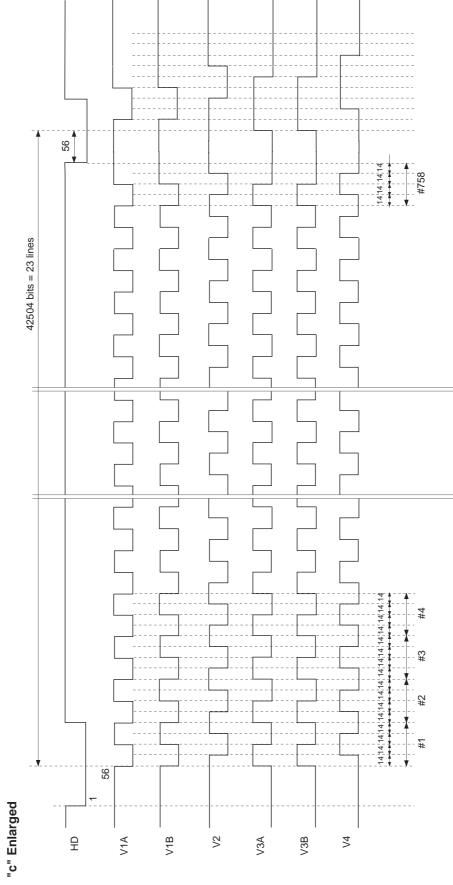
- 14 -



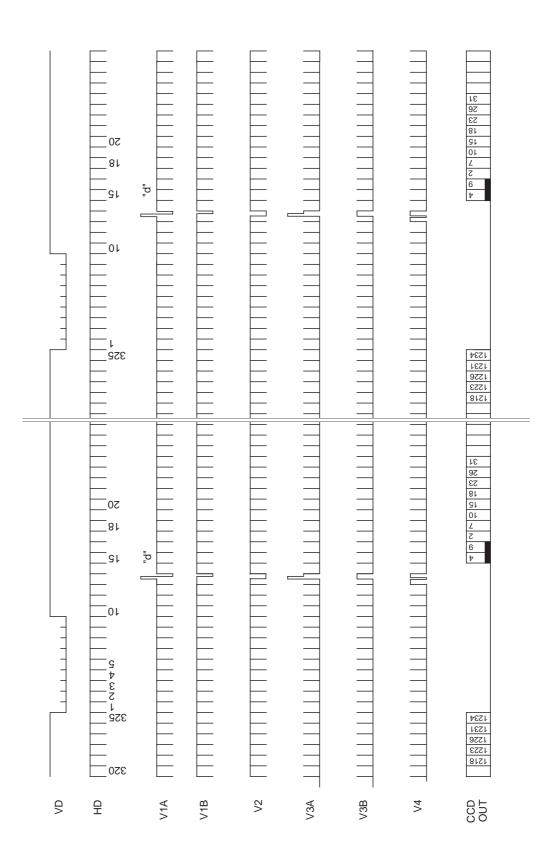


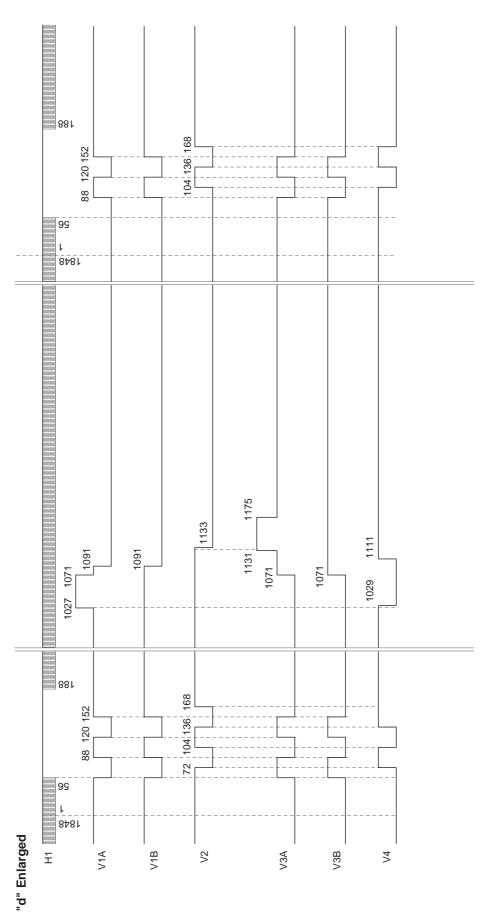
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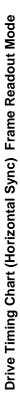


– 17 –





652		
30     30     30     30     30     132       132     132     188	52	52
		80
	80	
	-	
CLK RG SHP V1A V1B V2 V2	3A	V3B



20

32

ν4

Ŧ

H2

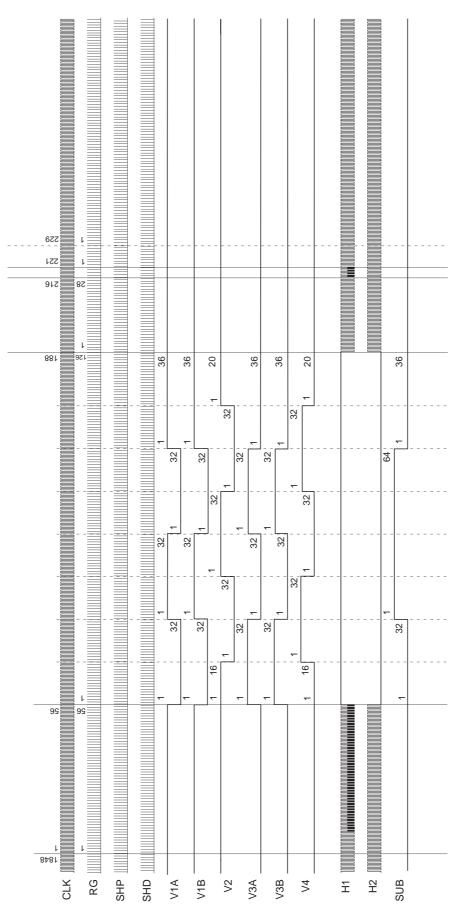
SUB

36

64

32

e Rate Readout Mode	
rizontal Sync) High Frame	
Drive Timing Chart (Hor	



# **Notes on Handling**

1) Static charge prevention

CCD image sensors are easily damaged by static discharge. Before handling be sure to take the following protective measures.

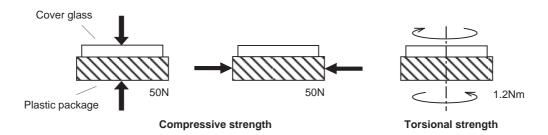
- a) Either handle bare handed or use non-chargeable gloves, clothes or material.
  - Also use conductive shoes.
- b) When handling directly use an earth band.
- c) Install a conductive mat on the floor or working table to prevent the generation of static electricity.
- d) lonized air is recommended for discharge when handling CCD image sensors.
- e) For the shipment of mounted substrates, use boxes treated for the prevention of static charges.

# 2) Soldering

- a) Make sure the package temperature does not exceed 80°C.
- b) Solder dipping in a mounting furnace causes damage to the glass and other defects. Use a 30W soldering iron with a ground wire and solder each pin in less than 2 seconds. For repairs and remount, cool sufficiently.
- c) To dismount an image sensor, do not use a solder suction equipment. When using an electric desoldering tool, use a thermal controller of the zero-cross On/Off type and connect it to ground.
- 3) Dust and dirt protection

Image sensors are packed and delivered by taking care of protecting its glass plates from harmful dust and dirt. Clean glass plates with the following operations as required, and use them.

- a) Perform all assembly operations in a clean room (class 1000 or less).
- b) Do not either touch glass plates by hand or have any object come in contact with glass surfaces. Should dirt stick to a glass surface, blow it off with an air blower. (For dirt stuck through static electricity ionized air is recommended.)
- c) Clean with a cotton bud and ethyl alcohol if grease stained. Be careful not to scratch the glass.
- d) Keep in a case to protect from dust and dirt. To prevent dew condensation, preheat or precool when moving to a room with great temperature differences.
- e) When a protective tape is applied before shipping, just before use remove the tape applied for electrostatic protection. Do not reuse the tape.
- 4) Installing (attaching)
  - a) Remain within the following limits when applying a static load to the package. Do not apply any load more than 0.7mm inside the outer perimeter of the glass portion, and do not apply any load or impact to limited

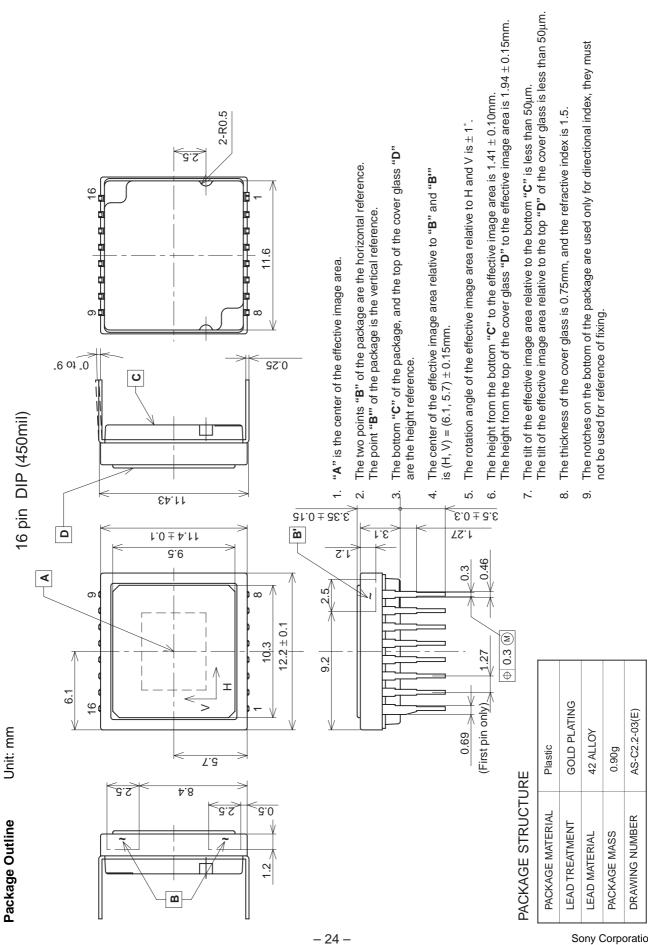


b) If a load is applied to the entire surface by a hard component, bending stress may be generated and the package may fracture, etc., depending on the flatness of the bottom of the package. Therefore, for installation, use either an elastic load, such as a spring plate, or an adhesive.

- c) The adhesive may cause the marking on the rear surface to disappear, especially in case the regulated voltage value is indicated on the rear surface. Therefore, the adhesive should not be applied to this area, and indicated values should be transferred to other locations as a precaution.
- d) The notch of the package is used for directional index, and that can not be used for reference of fixing. In addition, the cover glass and seal resin may overlap with the notch of the package.
- e) If the leads are bent repeatedly and metal, etc., clash or rub against the package, the dust may be generated by the fragments of resin.
- f) Acrylate anaerobic adhesives are generally used to attach CCD image sensors. In addition, cyanoacrylate instantaneous adhesives are sometimes used jointly with acrylate anaerobic adhesives. (reference)

# 5) Others

- a) Do not expose to strong light (sun rays) for long periods, as color filters will be discolored. When high luminous objects are imaged with the exposure level controlled by the electronic iris, the luminance of the image-plane may become excessive and discoloring of the color filter will possibly be accelerated. In such a case, it is advisable that taking-lens with the automatic-iris and closing of the shutter during the poweroff mode should be properly arranged. For continuous using under cruel condition exceeding the normal using condition, consult our company.
- b) Exposure to high temperature or humidity will affect the characteristics. Accordingly avoid storage or usage in such conditions.
- c) Brown stains may be seen on the bottom or side of the package. But this does not affect the CCD characteristics.



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